

tions as a support for the cylinder 10 and as a magnetic core for the attraction of a tracking element of the cursor control device. The pin 14 is made of brass or synthetic material, i.e., it should be of nonmagnetic material and is connected with the first iron core 12. The first iron core 12 is thereby movably connected with the cylinder 10.

[0022] The lower part consists of a pot-like element 18, preferably made of alumina or synthetic material, carrying a felt ring 20 at its upper surface. The felt ring may be provided with an additional specific amount of rubber. At its inner lower surface 22 the pot-like element 18 is provided with a second iron core 24 fixedly connected thereto and having an opening 26 in the middle thereof. The pot-like element 18 is, in turn, provided with an opening which is arranged coaxially to the opening 26, and a plate 28 is arranged at its outer bottom surface 30.

[0023] The pin 14 is inserted into the opening 26 of the second iron core 24 and passed through the coaxially arranged opening in the bottom portion of the pot-like element 18, where it is connected to the plate 28.

[0024] Thus, the second iron core 24 is slidably arranged around the pin 14 so that it may move up and down along the pin 14. The length of the pin 14 is dimensioned such that the distance between the lower surface of the first iron core 12 and the upper surface of the plate 28 is greater than the thickness of the second iron core 24.

[0025] The tracking element 32, having an iron shell, is arranged on top of the pot-like element 18 and is carried by the housing of the device (not shown), thereby not touching the pot-like element 18 in quiescent condition.

[0026] When the tracking element 32 is started to move slowly, the coil 16 will be energized.

[0027] The second iron core 24 is drawn up in the direction of the first iron core 12. Since the pot-like element 18 is fixedly connected to the second iron core 24, it will be drawn up as well. At the same time, the tracking element 32 is drawn in the direction of the second iron core 24, thus bringing the apparatus in an activated state (FIG. 2B). The felt ring 20 will touch the surface of the tracking element 32 thus producing a braking effect on the tracking element.

[0028] The braking effect can be released by de-energizing the coil, e.g., by a mouse click or the like.

[0029] When accelerating the movement of the tracking element 32, a point will be reached where a magnetic force will no longer exist. At this point, the second iron core 24 will no longer be attracted by the first iron core 12, and the pot-like element 18 will return into its non-activated state (FIG. 2A). Accordingly, the braking effect will cease and the brake will be released.

[0030] Since the iron cores 12, 24 have small dimensions, lying in the millimeter range, the pot-like element 18 can be adjusted to different sizes of tracking elements, i.e., smaller or greater pot-like elements 18 can be used. The ratio of dimensions between pot-like element and tracking element thereby is about 1:3.

[0031] Providing the felt ring 20 with an additional amount of rubber will increase its resisting force, but not the braking force. Using a "harder" brake covering, i.e., a

mixture of felt and rubber, or cork or the like, will need to employ a pulsing brake mechanism. This will be described with respect to FIG. 9 later.

[0032] FIG. 3 schematically depicts a second embodiment of an apparatus according to the invention. In this embodiment, the tracking element 32 is held in a depression 34 present in the housing 36 of the device by means of ball bearings 38. Within the housing 36, a cylinder 40, preferably made of synthetic material, is arranged below the tracking element 32. Inside the cylinder 40, there is mounted a coil 42. The upper end of the cylinder 40 carries a mat 44 being comprised of a fleece, cork, rubber or the like, the lower end of the cylinder 40 has the form of a round plate 46 which will serve as a stopper, what will be described in more detail below. The coil 42 is inserted into a magnetic ring 48, and a spring 50 is arranged between the ring 48 and the plate 46. The magnetic ring 48 is secured to the housing 36 and the coil 42 rests on the bottom of the housing 36.

[0033] When the tracking element 32 is started to move slowly, the coil 42 will be energized, the cylinder 40 will be moved in the direction of the tracking element 32 against the tension of the spring 50. The mat 44 will be pressed against the tracking element 32 thus creating a braking effect. As has already been mentioned above, the round plate 46 will thereby act as a stopper, limiting the movement of the cylinder 40 by abutting to the magnetic ring 48. As already discussed in view of the first embodiment, the braking force will cease when the tracking element is accelerated beyond a certain velocity where no magnetic force will be present any more. The cylinder 40 will, under the tension of spring 50, return into its non-activated position.

[0034] FIGS. 4A and 4B show the apparatus according to the second embodiment in its non-activated and activated state.

[0035] In FIGS. 5 and 6, there are shown still other embodiments of the arrangement shown in FIG. 3. FIG. 5 shows that three coils are arranged one beside the other on the side of the tracking element 32 being arranged within the depression 34. The advantage of such an arrangement is that the tracking element 32 can project far beyond half of the housing 36, without a risk that the tracking element 32 falls out of the depression when it is stopped. FIG. 6 depicts four coils according to the one presented in FIG. 3, which are arranged around the tracking element 32 at an angle of 90°, respectively.

[0036] FIGS. 7 to 9 are graphs showing the braking effect relative to the speed of the tracking element for several embodiments of the invention.

[0037] When looking at FIG. 7, two different behaviors are shown. The upper curve I describes the case that the tracking element is moved very quickly. In this case no braking effect occurs since the coil will not be energized due to the quick movement of the tracking element.

[0038] However, in case the tracking element is moved slowly, the coil will be energized and the braking effect will occur after a slight delay (point B in FIG. 7). Due to the braking effect, the speed of the tracking element will decrease to a nearly constant value (curve II in FIG. 7). The braking effect will continue until it will be stopped by the user by releasing the brake with a mouse click or the like (point C in FIG. 7). The hatched part in FIG. 7 illustrates the time the braking effect is present.

[0039] FIG. 8 depicts a typical graph when drawing with the apparatus according to the invention. First, the tracking